

## VEC\_OS.cpp

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```
//VEC OS
//#include <PalmOS.h>
//#include "VEC_OS_res.h"
#include "serial.h"
#include "supp.h"

#include "UCodes.h"
#include "B_ind.h"
#include "C_ind.h"
#include "P_ind.h"
/*****
 * Constants
 *****/
#define appFileCreator          'VECOS '
#define appVersionNum          0x01
#define appPrefID              0x00
#define appPrefVersionNum      0x01
#define minVersion    sysMakeROMVersion(2,0,0,sysROMStageRelease,0)

#define RECEIVE_BLK_SIZE      10 //set this to 64
#define BAUD_RATE              9600

/*****
 * Globals
 *****/
Boolean gSerialPortOpen;
UInt16  gSerialPortId;
Err      gSerialPortOpenErr;
Err      gSerialPortCloseErr;
Err      gSerialPortSendErr;
Err      gSerialPortReceiveErr;
int      gNumBytesSent;
UInt8    gBytesToReceive = RECEIVE_BLK_SIZE;
UInt32   gDataBuffer;
Char*    gReceiveBuffer;
Char     gReceiveData[RECEIVE_BLK_SIZE];
UInt8    gVolume; //control bit to send out
UInt8    gSpeed; //0=Vehicle Speed
UInt8    gNumDTCs; //1=#DTCs
UInt8    gSensLR; //2=Sensor1-Left Rear
UInt8    gSensRR; //3=Sensor2-Right Rear
UInt8    gSensLS; //4=Sensor3-Left Side
UInt8    gSensRS; //5=Sensor4-Right Side
UInt8    gSensF; //6=Sensor5-Front
UInt8    gELMerr; //7=ELM error
UInt8    gWBerr; //8=Winbond Error
UInt8    gSensErr; //9=Sensor Error
UInt8    gDTC[36]; //10-45=DTC 1.1-18.2 :two bytes each
Char     gVIN[17]; //46-62 VIN#
UInt8    gInstance;
Boolean  gDispLR;
```

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```
Boolean gDispRR;
Boolean gDispLS;
Boolean gDispRS;
Boolean gDispF;
Boolean gFirst;

/*****
 * Prototypes
 *****/
Err RomVersionCompatible(UInt32 requiredVersion, UInt16 launchFlags);
void * GetObjectPtr(UInt16 formID);
void MainFormInit(FormPtr /*frmP*/);
Boolean MenuCommand(UInt16 command);
Boolean MainFormHandleEvent(EventPtr eventP);
Boolean AppHandleEvent(EventPtr eventP);
void AppEventLoop(void);
Err AppStart(void);
void AppStop(void);static UInt32 StarterPalmMain(UInt16 cmd, MemPtr, UInt16 launchFlags);
UInt32 PilotMain(UInt16 cmd, MemPtr cmdPBP, UInt16 launchFlags);
void SerialReceive();
void Init();
void HandleDTCs();

/*****
 * Structs
 *****/
typedef struct
{
    UInt8 prefType;
} StarterPreferenceType;

typedef struct
{
    UInt8 appInfoType;
} StarterAppInfoType;

typedef StarterAppInfoType* StarterAppInfoPtr;

/*****
 * Functions
 *****/

/*****
 * handleDTCs - if there's a DTC reported, this allows it to be displayed
 *
 * returns:nothing
 *****/
void HandleDTCs()
{
    int test,tc;
    char* warning;
    char Error[] = "Code not found";
```

```
for(int i=0;i<gNumDTCs;i=i+2){
    tc=gDTC[i]; //not sure if this will work or not

    test = tc & 0xF000;           // isolate the upper four bits to determine
                                // which code set to use (P, C, B, or U)
    tc &= 0x0FFF;               // isolate bits 0-5 to determine which code to use
    switch(test)
    {
        case 0x0000:
        case 0x1000:
        case 0x2000:
        case 0x3000:    if(tc > 0x2138) warning = Error;
                        else if(tc == 0x1501)
                        {
                            if(gVIN[BOD] == 'V') warning = &PCodes[30638];
                            else warning = &PCodes[30661];
                            break;
                        }
                        else if(tc == 0x1971)
                        {
                            if(gVIN[BOD] == 'J') warning = &PCodes[36363];
                            else warning = &PCodes[33630];
                        }
                        else if(tc == 0x1972)
                        {
                            if((gVIN[BOD] == 'V') || (gVIN[BOD] == 'Z')) warning = &PCodes
[36441];

                            else warning = &PCodes[33391];
                        }
                        else if(tc == 0x1890)
                        {
                            if((gVIN[YEAR] == 'V') || (gVIN[YEAR] == 'W')) warning = &
PCodes[38503];

                            else warning = &PCodes[38526];
                        }
                        else warning = P_ind[tc]; // P-code
                        break;

        case 0x4000:
        case 0x5000:
        case 0x6000:
        case 0x7000:    if(tc > 0x1788) warning = Error;
                        else if(tc == 0x0245)
                        {
                            if(gVIN[DIV] == 'C') warning = &CCodes[1301];
                            else warning = &CCodes[1328];
                        }
                        else warning = C_ind[tc]; // C-code
                        break;

        case 0x8000:
        case 0x9000:
```

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case 0xA000:
case 0xB000:    if(tc == 0x1760)                // B-code
                {
                    if(gVIN[BOD] == 'H') warning = &BCodes[8079];
                    else warning = &BCodes[5814];
                }
                else if(tc == 0x3642) warning = &BCodes[16221];
                else if(tc == 0x3793) warning = &BCodes[16258];
                else if(tc == 0x3833 || tc == 0x3832) warning = &BCodes[16290];
                else if(tc == 0x3935) warning = &BCodes[16321];
                else if(tc > 3527) warning = Error;
                else warning = B_ind[tc];
                break;

case 0xC000:
case 0xD000:
case 0xE000:
case 0xF000:                // U-code
                if(tc < 0x1000) warning = Error;
                else
                {
                    switch(tc)
                    {
                        case 0x1255:            // same as U1000
                        case 0x1000:            warning = &UCodes[0]; break;
                        case 0x1001:            warning = &UCodes[34]; break;
                        case 0x1016:            if(gVIN[BOD] == '5' || gVIN[BOD] == '6')
                                                warning = &UCodes[84];
                                                else warning = &UCodes[123];
                                                break;

                        case 0x1026:            warning = &UCodes[155]; break;
                        case 0x1040:            warning = &UCodes[189]; break;
                        case 0x1041:            warning = &UCodes[229]; break;
                        case 0x1042:            warning = &UCodes[256]; break;
                        case 0x1056:            warning = &UCodes[311]; break;
                        case 0x1064:            warning = &UCodes[343]; break;
                        case 0x1065:            warning = &UCodes[375]; break;
                        case 0x1066:            warning = &UCodes[407]; break;
                        case 0x1088:            warning = &UCodes[439]; break;
                        case 0x1096:            warning = &UCodes[471]; break;
                        case 0x1128:            warning = &UCodes[503]; break;
                        case 0x1129:            warning = &UCodes[535]; break;
                        case 0x1144:            warning = &UCodes[567]; break;
                        case 0x1145:            warning = &UCodes[599]; break;
                        case 0x1146:            warning = &UCodes[626]; break;
                        case 0x1152:            if(gVIN[BOD] == '1' || gVIN[BOD] == 'E'
                                                || gVIN[BOD] == 'H' || gVIN[BOD] == 'J'
                                                || gVIN[BOD] == 'K') warning = &
UCodes[692];

                                                else warning = &UCodes[654];
                                                break;

                        case 0x1153:            warning = &UCodes[717]; break;
                        case 0x1160:            warning = &UCodes[749]; break;

```

```
        case 0x1161:    warning =    &UCodes[781];    break;
        case 0x1162:    warning =    &UCodes[810];    break;
        case 0x1163:    warning =    &UCodes[846];    break;
        case 0x1164:    warning =    &UCodes[880];    break;
        case 0x1166:    warning =    &UCodes[918];    break;
        case 0x1168:    warning =    &UCodes[950];    break;
        case 0x1169:    warning =    &UCodes[977];    break;
        case 0x1170:    warning =    &UCodes[1009];   break;
        case 0x1176:    warning =    &UCodes[1058];   break;
        case 0x1192:    warning =    &UCodes[1085];   break;
        case 0x1193:    warning =    &UCodes[1121];   break;
//
        case 0x1255:    warning =    &UCodes[1155];   break;
        case 0x1300:    warning =    &UCodes[1184];   break;
        case 0x1301:    warning =    &UCodes[1208];   break;
        case 0x1304:    warning =    &UCodes[1233];   break;
        case 0x1305:    warning =    &UCodes[1261];   break;
        case 0x1500:    warning =    &UCodes[1291];   break;
        case 0x1715:    // Same as U1713
        case 0x1713:    warning =    &UCodes[1331];   break;
        case 0x1716:    // Same as U1714
        case 0x1714:    warning =    &UCodes[1390];   break;
        case 0x1800:    warning =    &UCodes[1451];   break;
        case 0x2000:    warning =    &UCodes[1499];   break;
        case 0x2001:    warning =    &UCodes[1532];   break;
        case 0x2002:    warning =    &UCodes[1565];   break;
        case 0x2003:    warning =    &UCodes[1582];   break;
        case 0x2004:    warning =    &UCodes[1600];   break;
        case 0x2005:    warning =    &UCodes[1618];   break;
        case 0x2006:    warning =    &UCodes[1637];   break;
        case 0x2007:    warning =    &UCodes[1656];   break;
        case 0x2050:    warning =    &UCodes[1676];   break;
        case 0x2100:    warning =    &UCodes[1720];   break;
        case 0x2102:    warning =    &UCodes[1755];   break;
        case 0x2103:    warning =    &UCodes[1795];   break;
        case 0x2104:    warning =    &UCodes[1836];   break;
        case 0x2105:    warning =    &UCodes[1866];   break;
        case 0x2106:    warning =    &UCodes[1903];   break;
        case 0x2107:    warning =    &UCodes[1939];   break;
        case 0x2108:    warning =    &UCodes[1984];   break;
        case 0x2150:    warning =    &UCodes[2018];   break;
        case 0x2151:    warning =    &UCodes[2061];   break;
        case 0x2153:    warning =    &UCodes[2102];   break;
        default:        warning =    &UCodes[34];     break;
    } // end switch
} // end else
} //end switch

    FrmCustomAlert(OBDAlert,warning,"","");

} //end for
```

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```
}
/*****
 * Init - initializes everything on main form
 *
 * returns:nothing
 *****/
void Init()
{
    FormPtr frmP;
    UInt8   ObjectIndex;
    frmP=FrmGetActiveForm();//get active form
    ObjectIndex=FrmGetObjectIndex(frmP,MainSerialConnectionBitMap);//get index of serial connection
bitmap
    FrmHideObject(frmP,ObjectIndex);
    gDispLR=true;
    gDispRR=true;
    gDispLS=true;
    gDispRS=true;
    gDispF=true;
    gInstance=0;
    gFirst=true;
    gVolume=0+48;
}
/*****
 * SerialReceive - receives data through serial port
 *
 * returns:nothing
 *****/
void SerialReceive()
{
    FormPtr frmP;
    UInt8   ObjectIndex;

    frmP=FrmGetActiveForm();//get active form
    ObjectIndex=FrmGetObjectIndex(frmP,MainSerialConnectionBitMap);//get index of serial connection
bitmap
    gSerialPortOpenErr = SrmOpen(serPortCradlePort,BAUD_RATE,&gSerialPortId);//open the serial port
    FrmShowObject(frmP,ObjectIndex);

    if (gSerialPortOpenErr == errNone) //if there's no error opening port
    {
        gSerialPortOpen=true; //set PortOpen = true
        //send volume control as synch byte
        gNumBytesSent = SrmSend(gSerialPortId, &gVolume, 1, &gSerialPortSendErr);
        if(gNumBytesSent != 1) FrmCustomAlert(SerialPortAlert,"Number of bytes sent does
not match intended length.", "", "");
        if(gSerialPortSendErr != errNone)
            SerialPortSendError(gSerialPortSendErr);
        else FrmAlert(SuccessAlert);

        UInt32 bytesReceived;
        gSerialPortReceiveErr = SrmReceiveWait(gSerialPortId,RECEIVE_BLK_SIZE,
```

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SysTicksPerSecond()*6);
    if (gSerialPortReceiveErr != errNone)
        SerialPortReceiveError(gSerialPortReceiveErr,&gSerialPortId);
    else{
        gReceiveBuffer=gReceiveData;
        bytesReceived = SrmReceive(gSerialPortId,gReceiveBuffer,RECEIVE_BLK_SIZE,
SysTicksPerSecond()*6,&gSerialPortReceiveErr);
        if (gSerialPortReceiveErr != errNone){
            FrmCustomAlert(SerialPortAlert,"Problem with SrmReceive","", "");
            SerialPortReceiveError(gSerialPortReceiveErr,&gSerialPortId);}
        else{
            FrmCustomAlert(SerialPortAlert,"The data has been received successfully.",
"", "");

            gSpeed=gReceiveData[0];        //Vehicle speed
            displaySpeed(gSpeed); //display speed
            gNumDTCs=gReceiveData[1];      // #DTCs
            displayDTCs(gNumDTCs); //display # of DTCs

            gSensLR=gReceiveData[2];       //Sensor1-Left Rear
            gSensRR=gReceiveData[3];       //Sensor2-Right Rear
            gSensLS=gReceiveData[4];       //Sensor3-Left Side
            gSensRS=gReceiveData[5];       //Sensor4-Right Side
            gSensF=gReceiveData[6];        //Sensor5-Front
            gELMerr=gReceiveData[7];       //ELM error
            if(gELMerr && gELMerr!='0')     //if ELM error, display alert
                FrmCustomAlert(SystemErrorAlert,"There is a problem with the ELM
circuit. Make sure everything is connected properly.", "", "");
            gWBerr=gReceiveData[8];        //WinBond error
            if(gWBerr && gWBerr!='0')       //if WinBond error, display alert
                FrmCustomAlert(SystemErrorAlert,"There is a problem with the WinBond
circuit.", "", "");
            gSensErr=gReceiveData[9];      //Sensor error
            if(gSensErr && gSensErr!='0')   //if there's a prob with any of the sensors
                FrmCustomAlert(SystemErrorAlert,"There is a problem with one of the
sensors.", "", "");
            //          for(int i=0;i<37;i++){
            //              gDTC[i]=gReceiveData[10+i]; //DTC 1.1-18.2, two bytes each
            //          }
            //          for(int i=0;i<19;i++){
            //              ggVIN[i]=gReceiveData[46+i]; //vehicles gVIN number
            //          }

            SrmReceiveFlush (gSerialPortId,0); //flush the receive FIFO
        }
    }

    if (gSerialPortOpen)
        gSerialPortCloseErr = SrmClose(gSerialPortId);
    if (gSerialPortCloseErr == errNone) {
        gSerialPortOpen=false; //port open = false
        FrmAlert(Success2Alert);
        FrmHideObject(frmP, ObjectIndex);}
    else SerialPortCloseError(gSerialPortCloseErr);
}

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```
    else SerialPortOpenError(gSerialPortOpenErr, &gSerialPortId);
}
/*****
* RomVersionCompatible - checks that ROM version meets minimum requirements
*
* input: requiredVersion - minimum rom version required
* launchFlags - indicate if the application UI is initialized.
*
* returns: error code or zero if rom is compatible
*****/
Err RomVersionCompatible(UInt32 requiredVersion, UInt16 launchFlags)
{
    UInt32 romVersion;

    FtrGet(sysFtrCreator, sysFtrNumROMVersion, &romVersion);
    if (romVersion < requiredVersion)
    {
        if((launchFlags & (sysAppLaunchFlagNewGlobals | sysAppLaunchFlagUIApp)) ==
            (sysAppLaunchFlagNewGlobals | sysAppLaunchFlagUIApp))
        {
            FrmAlert (RomIncompatibleAlert);
            if(romVersion < minVersion)
            {
                AppLaunchWithCommand(sysFileCDefaultApp, sysAppLaunchCmdNormalLaunch, NULL
);
            }
        }
        return sysErrRomIncompatible;
    }
    return errNone;
}

/*****
* GetObjectPtr - returns a pointer to an object in the current form.
*
* input: formID - id of the form to display
*****/
void * GetObjectPtr(UInt16 formID)
{
    FormPtr frmP;

    frmP = FrmGetActiveForm();
    return FrmGetObjectPtr(frmP, FrmGetObjectIndex(frmP, formID));
}

/*****
* MainFormInit - initializes the MainForm form.
*
* input: frm - pointer to the MainForm form.
*****/
void MainFormInit(FormPtr /*frmP*/)
{
```



```
}

/*****
 * MenuCommand - performs the menu command specified.
 *
 * input: command - menu item id
 *****/
Boolean MenuCommand(UInt16 command)
{
    Boolean handled = false;
    FormPtr frmP;

    switch (command)
    {
        case MainOptionsAbout:
            MenuEraseStatus(0);
            frmP = FrmInitForm (AboutForm);
            FrmDoDialog (frmP);
            FrmDeleteForm (frmP);
            handled = true;
            break;

        case MainOptionsVECTeam:
            MenuEraseStatus(0);
            frmP = FrmInitForm (VECTeamForm);
            FrmDoDialog (frmP);
            FrmDeleteForm (frmP);
            handled = true;
            break;
    }
    return handled;
}

/*****
 * MainFormHandleEvent - event handler for the MainForm
 *
 * input: eventP - a pointer to an EventType structure
 *
 * returns:true if event has handle and shouldn't be passed to higher level handler.
 *****/
Boolean MainFormHandleEvent(EventPtr eventP)
{
    Boolean handled = false;
    FormPtr frmP;
    UInt8    ObjectIndex;

    switch (eventP->eType)
    {
        case menuEvent:
            return MenuCommand(eventP->data.menu.itemID);

        case frmOpenEvent:
```

```
    frmP = FrmGetActiveForm();
    MainFormInit(frmP);
    FrmDrawForm(frmP);
    handled = true;
    break;
case ctlSelectEvent:
    if(eventP->data.ctlSelect.controlID == MainBtnExitButton) //Exit button
    {
        if (gSerialPortOpen) gSerialPortCloseErr = SrmClose(gSerialPortId);
        eventP->eType = appStopEvent;
    }
    else if (eventP->data.ctlSelect.controlID == MainBtnDTCsButton) //Log Button
    {
        SerialReceive();
        //sdasdf
        //HandleDTCs();
    }
    else if (eventP->data.ctlSelect.controlID ==
MainSldrVolumeFeedbackSliderControl)
    {
        //UInt8 result;
        //result= (UInt8)eventP->data.ctlSelect.value;
        //displaySpeed(result); //for testing
        gVolume = (UInt8)eventP->data.ctlSelect.value;
        gVolume = gVolume+48; //ascii char
    }
    handled = true;
    break;
case nilEvent:
    if(!gFirst) Init();
    //test

    frmP=FrmGetActiveForm();//get active form
    //end test
    switch (gInstance){
        case 0:
            //driver rear sensor
            if(gSensLR==1 || gSensLR==2){
                ObjectIndex=FrmGetObjectIndex(frmP,MainCarDriverRearBitMap);
                if(gDispLR){
                    FrmHideObject(frmP,ObjectIndex);
                    gDispLR=false;
                } else if (!gDispLR) {
                    FrmShowObject(frmP,ObjectIndex);
                    gDispLR=true;
                }
            }
            //passenger rear sensor
            if(gSensRR==1 || gSensRR==2){
                ObjectIndex=FrmGetObjectIndex(frmP,MainCarPassengerRearBitMap);
                if(gDispRR){
                    FrmHideObject(frmP,ObjectIndex);
                    gDispRR=false;
```

```
        } else if (!gDispRR) {
            FrmShowObject(frmP, ObjectIndex);
            gDispRR=true;
        }
    }
    //driver middle sensor
    if(gSensLS==1 || gSensLS==2){
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarDriverMiddleBitMap);
        if(gDispLS){
            FrmHideObject(frmP, ObjectIndex);
            gDispLS=false;
        } else if (!gDispLS) {
            FrmShowObject(frmP, ObjectIndex);
            gDispLS=true;
        }
    }
    //passenger middle sensor
    if(gSensRS==1 || gSensRS==2){
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarPassengerMiddleBitMap);
        if(gDispRS){
            FrmHideObject(frmP, ObjectIndex);
            gDispRS=false;
        } else if (!gDispRS) {
            FrmShowObject(frmP, ObjectIndex);
            gDispRS=true;
        }
    }
    //front sensor
    if(gSensF==1 || gSensF==2){
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarFrontBitMap);
        if(gDispF){
            FrmHideObject(frmP, ObjectIndex);
            gDispF=false;
        } else if (!gDispF) {
            FrmShowObject(frmP, ObjectIndex);
            gDispF=true;
        }
    }

    gInstance=1;
    break;
case 1:
    //driver rear sensor
    if(gSensLR==2){
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarDriverRearBitMap);
        if(gDispLR){
            FrmHideObject(frmP, ObjectIndex);
            gDispLR=false;
        } else if (!gDispLR) {
            FrmShowObject(frmP, ObjectIndex);
            gDispLR=true;
        }
    }
    //passenger rear sensor
    if(gSensRR==2){
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarPassengerRearBitMap);
        if(gDispRR){
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```
        FrmHideObject(frmP, ObjectIndex);
        gDispRR=false;
    } else if (!gDispRR) {
        FrmShowObject(frmP, ObjectIndex);
        gDispRR=true;
    }
}
//driver middle sensor
if(gSensLS==2){
    ObjectIndex=FrmGetObjectIndex(frmP, MainCarDriverMiddleBitMap);
    if(gDispLS){
        FrmHideObject(frmP, ObjectIndex);
        gDispLS=false;
    } else if (!gDispLS) {
        FrmShowObject(frmP, ObjectIndex);
        gDispLS=true;
    }
}
//passenger middle sensor
if(gSensRS==2){
    ObjectIndex=FrmGetObjectIndex(frmP, MainCarPassengerMiddleBitMap);
    if(gDispRS){
        FrmHideObject(frmP, ObjectIndex);
        gDispRS=false;
    } else if (!gDispRS) {
        FrmShowObject(frmP, ObjectIndex);
        gDispRS=true;
    }
}
//front sensor
if(gSensF==2){
    ObjectIndex=FrmGetObjectIndex(frmP, MainCarFrontBitMap);
    if(gDispF){
        FrmHideObject(frmP, ObjectIndex);
        gDispF=false;
    } else if (!gDispF) {
        FrmShowObject(frmP, ObjectIndex);
        gDispF=true;
    }
}

    gInstance=2;
    break;
case 2:
    //receive data here
    gInstance=0;
    break;
}

if(gSensLR==0 && !gDispLR){ //if there's no longer a warning, stop blinking
    ObjectIndex=FrmGetObjectIndex(frmP, MainCarDriverRearBitMap);
    FrmShowObject(frmP, ObjectIndex);
}
if(gSensRR==0 && !gDispRR){ //if there's no longer a warning, stop blinking
    ObjectIndex=FrmGetObjectIndex(frmP, MainCarPassengerRearBitMap);
    FrmShowObject(frmP, ObjectIndex);
}
```

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    }
    if(gSensLS==0 && !gDispLS){ //if there's no longer a warning, stop blinking
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarDriverMiddleBitMap);
        FrmShowObject(frmP,ObjectIndex);
    }
    if(gSensRS==0 && !gDispRS){ //if there's no longer a warning, stop blinking
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarPassengerMiddleBitMap);
        FrmShowObject(frmP,ObjectIndex);
    }
    if(gSensF==0 && !gDispF){ //if there's no longer a warning, stop blinking
        ObjectIndex=FrmGetObjectIndex(frmP,MainCarFrontBitMap);
        FrmShowObject(frmP,ObjectIndex);
    }

    handled=true;
    break;

    default:
        break;
}
return handled;
}

/*****
* AppHandleEvent - loads form resources and sets event handler for the form loaded.
*
* input: event - a pointer to an EventType structure
*
* returns:true if event has handle and shouldn't be passed to higher level handler.
*****/
Boolean AppHandleEvent(EventPtr eventP)
{
    UInt16 formId;
    FormPtr frmP;

    if(eventP->eType == frmLoadEvent)
    {
        //load form resource
        formId = eventP->data.frmLoad.formID;
        frmP = FrmInitForm(formId);
        FrmSetActiveForm(frmP);

        // Set the event handler for the form. The handler of the currently
        // active form is called by FrmHandleEvent each time it receives an
        // event.
        switch (formId)
        {
            case MainForm:
                FrmSetEventHandler(frmP, MainFormHandleEvent);
                break;

            default:
                break;
        }
    }
}

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```
    }
    return true;
}
return false;
}

/*****
 * AppEventLoop - event loop for the application.
 *
 * no params
 *****/
void AppEventLoop(void)
{
    UInt16 error;
    EventType event;

    do
    {
        EvtGetEvent(&event, SysTicksPerSecond()/3); //3 times per second
        if(! SysHandleEvent(&event))
            if(! MenuHandleEvent(0,&event,&error))
                if(! AppHandleEvent(&event))
                    FrmDispatchEvent(&event);
    }while(event.eType != appStopEvent);
}

/*****
 * AppStart - Gets current application's preferences.
 *
 * returns:Err value 0 if nothing went wrong
 *****/
Err AppStart(void)
{
    StarterPreferenceType prefs;
    UInt16 prefsSize;

    // Read the saved preferences / saved-state information.
    prefsSize = sizeof(StarterPreferenceType);
    if(PrefGetAppPreferences(appFileCreator, appPrefID, &prefs, &prefsSize, true) !=
        noPreferenceFound)
    {
    }
    return errNone;
}

/*****
 * AppStop - saves current state of the application.
 *
 * no params
 *****/
void AppStop(void)
```

```
{
    StarterPreferenceType prefs;

    // Write the saved preferences / saved-state information. This data
    // will be backed up during a HotSync.
    PrefSetAppPreferences (appFileCreator, appPrefID, appPrefVersionNum, &prefs, sizeof(
prefs), true);

    FrmCloseAllForms();
}

/*****
 * StarterPalmMain - called by PilotMain when program is loaded.
 *
 * input:    cmd - extra commands
 *           launchFlags - indicate if the application UI is initialized
 *****/
UInt32 StarterPalmMain(UInt16 cmd, MemPtr, UInt16 launchFlags)
{
    Err error;

    error = RomVersionCompatible (minVersion, launchFlags);
    if(error) return (error);

    switch (cmd)
    {
        case sysAppLaunchCmdNormalLaunch:
            error = AppStart();
            if(error) return (error);

            FrmGotoForm(MainForm);
            //SerialInit();
            AppEventLoop();
            AppStop();
            break;

        default:
            break;
    }

    return errNone;
}

/*****
 * PilotMain - function that executes when program is loaded
 *
 * input:    cmd - extra commands
 *           cmdPBP - ptr to location in memory with code
 *           launchFlags - indicate if the application UI is initialized
 *****/
UInt32 PilotMain(UInt16 cmd, MemPtr cmdPBP, UInt16 launchFlags)
```

```
{  
    return StarterPalmMain(cmd, cmdPBP, launchFlags);  
}
```